

Physical Carrier Sense in Vehicular Ad-hoc Networks

Razvan Stanica, Emmanuel Chaput, André-Luc Beylot

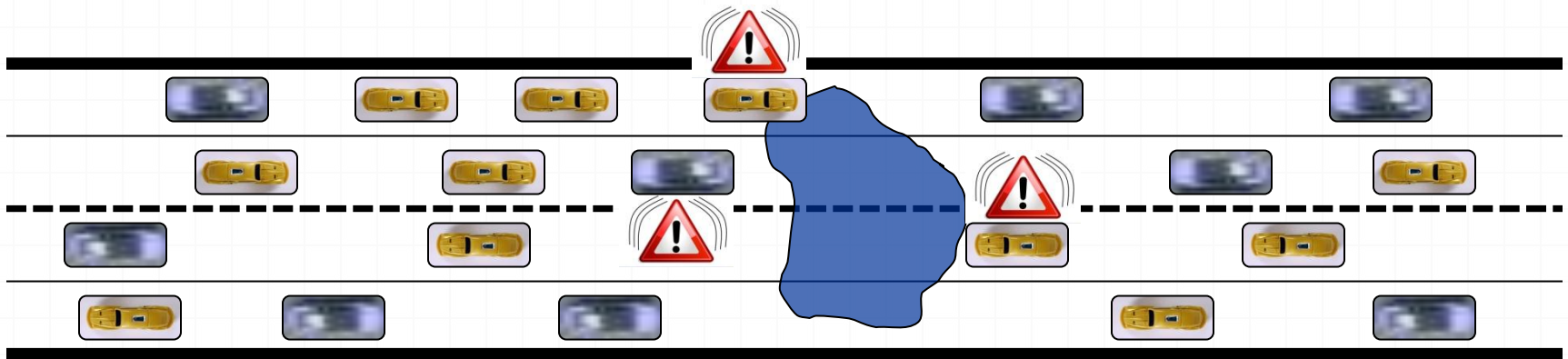
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Systems
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- ❑ Safety Communication in Vehicular Networks**
- ❑ Particularities of the VANET Control Channel**
- ❑ The Importance of the Carrier Sense Range**
- ❑ Adaptive Carrier Sense Threshold**

VANET objective: Building an accurate image of the exterior world



❑ Cooperative Awareness Message (CAM)

❑ Decentralised Environmental Notification (DEN)

Safety V2V

Control Channel

Carrier Sense Range

Adaptive CS

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Physical Carrier Sense in Vehicular Ad-hoc Networks

Safety Applications

- Intersection Collision Warning
- Emergency Electronic Brake Lights
- Approaching Emergency Vehicle
- Lane Change Assistant
- Left-Turn Collision Warning

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USA Spectrum Allocation

CH172	CH174	CH176	CH178	CH180	CH182	CH184
5.860	5.870	5.880	5.890	5.900	5.910	5.920
G5SC4	G5SC3	G5SC1	G5SC2	G5CC		

Europe Spectrum Allocation

- ❑ Service channels (SCH) – non-safety (usually IP-based) applications
 - ❑ Control channel (CCH) – safety applications

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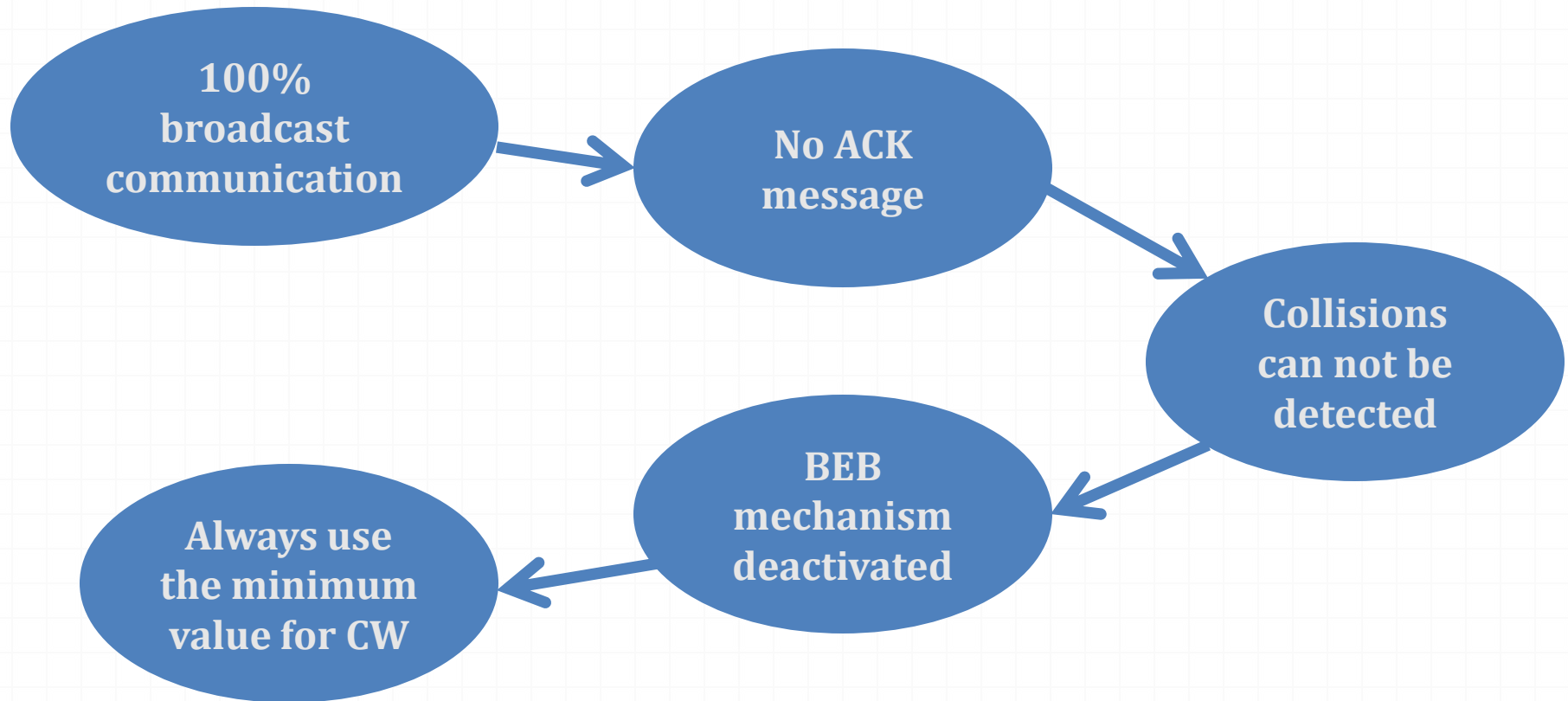
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Safety beaconing

- A beacon expires if the next CAM is produced
- No exposed terminals
- Practically no internal contention on the CCH
- MAC delay automatically considered in the expiration probability
- Metric of interest: reception probability

IEEE 802.11p on the CCH



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Congestion Control

- ❑ Reduce Beaconsing Frequency

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Congestion Control

- Reduce Beacons Frequency
- Increase Data Rate

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Congestion Control

- Reduce Beacons Frequency
- Increase Data Rate
- Control Transmission Power

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Congestion Control

- Reduce Beacons Frequency
- Increase Data Rate
- Control Transmission Power
- Modify Back-off Mechanism

Congestion Control

- Reduce Beacons Frequency
- Increase Data Rate
- Control Transmission Power
- Modify Back-off Mechanism
- Adapt Carrier Sensing

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Carrier Sense in IEEE 802.11

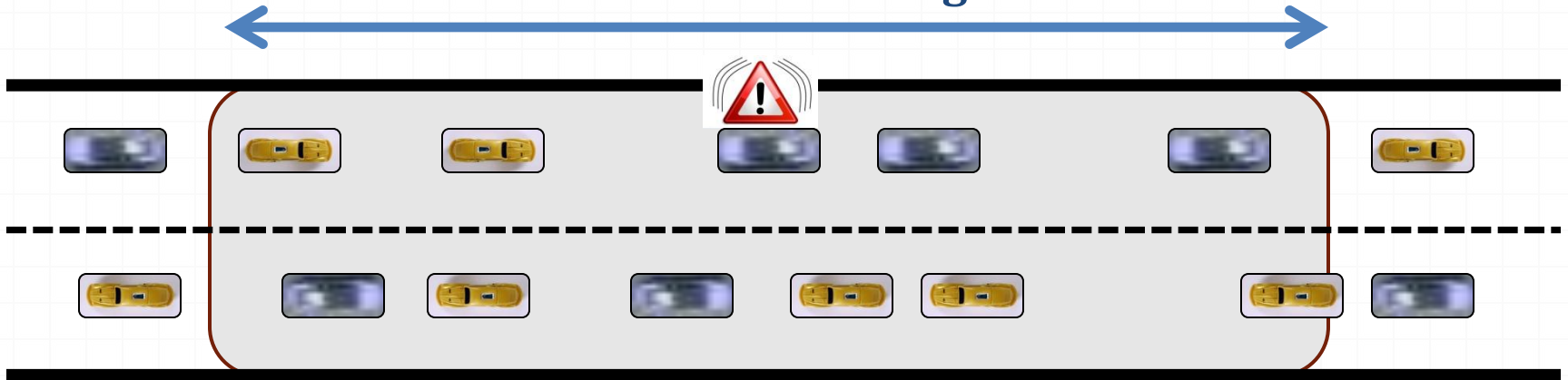
❑ MAC Layer – Network Allocation Vector

- based on the RTS/CTS handshake
- unusable on the broadcast CCH

❑ PLCP Layer – Clear Channel Assignment

- header detection
- energy detection

Carrier Sense Range



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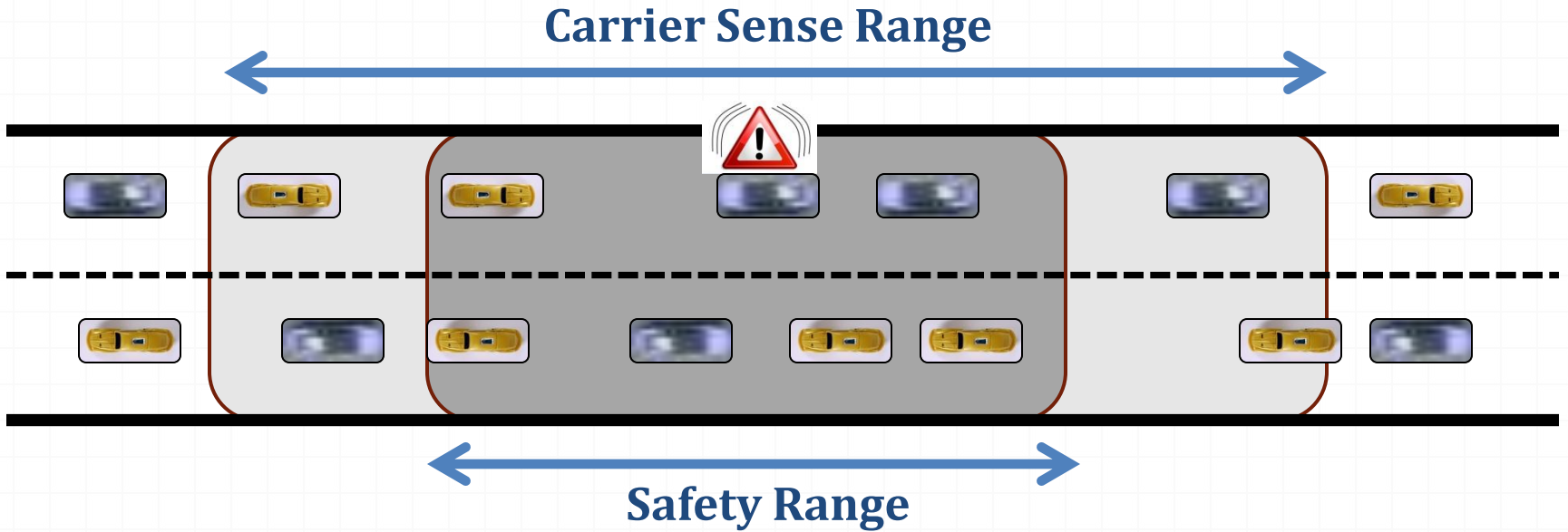
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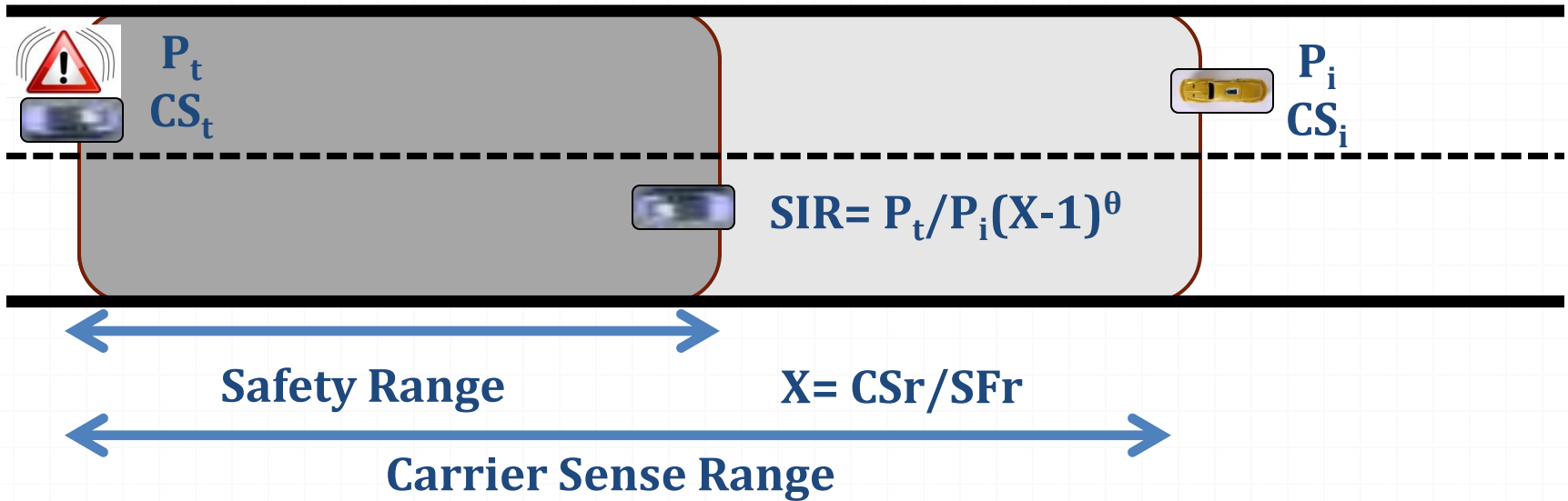
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Worst Case Scenario



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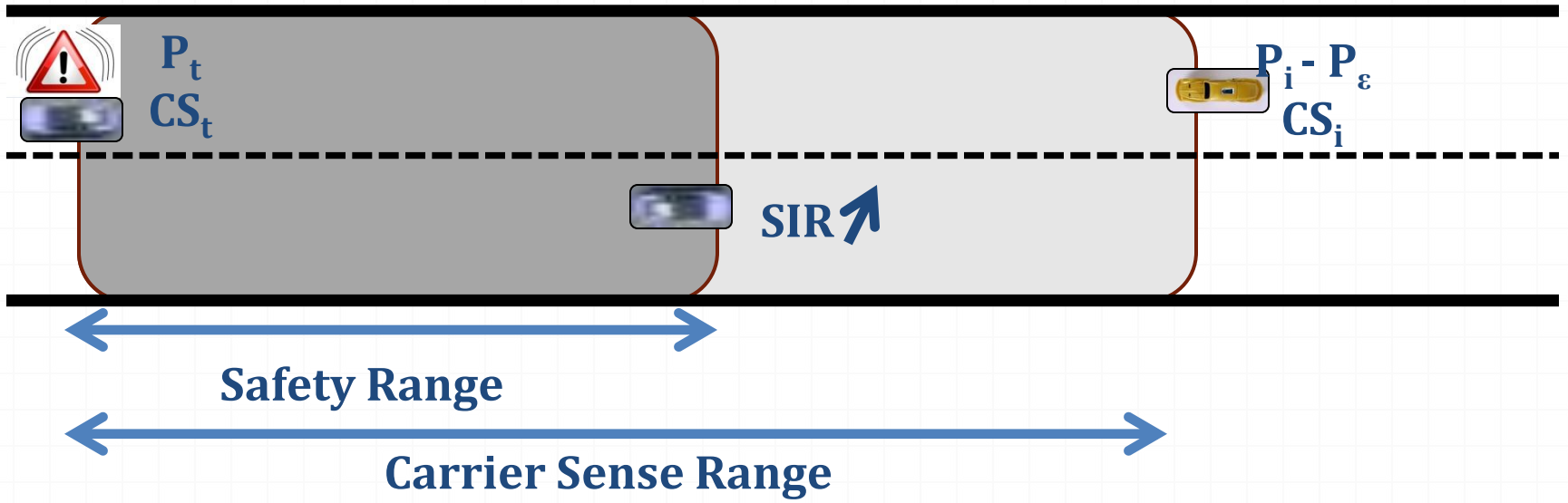
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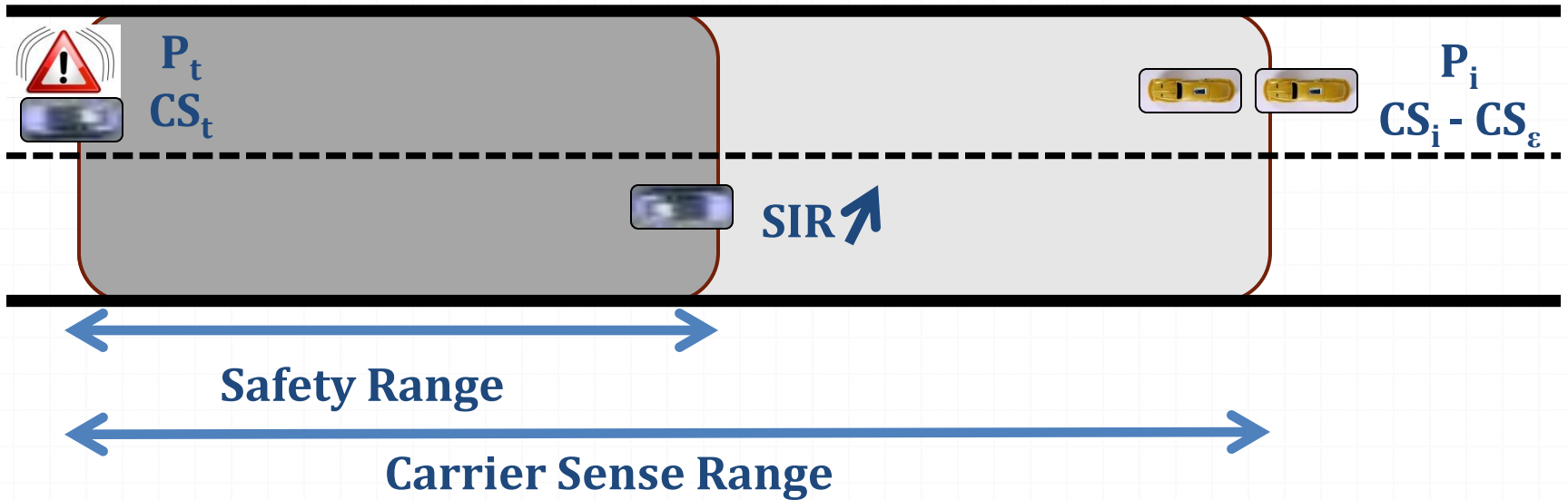
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Transmission Power Control



Carrier Sense Threshold Control



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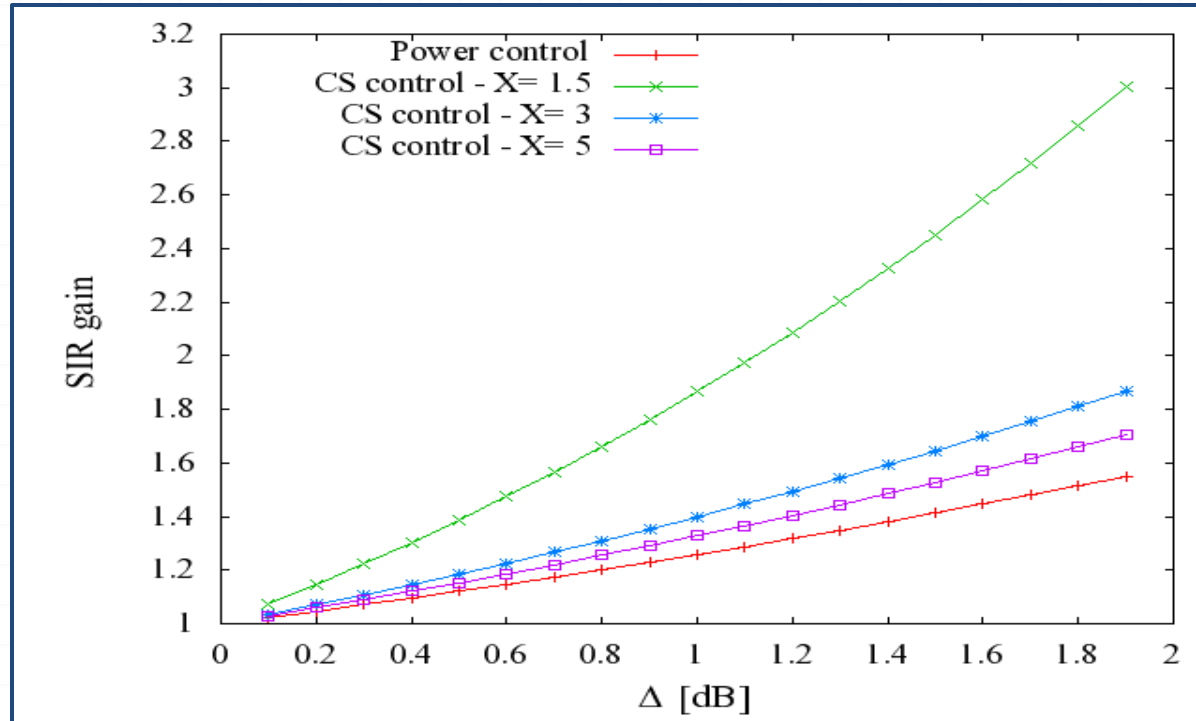
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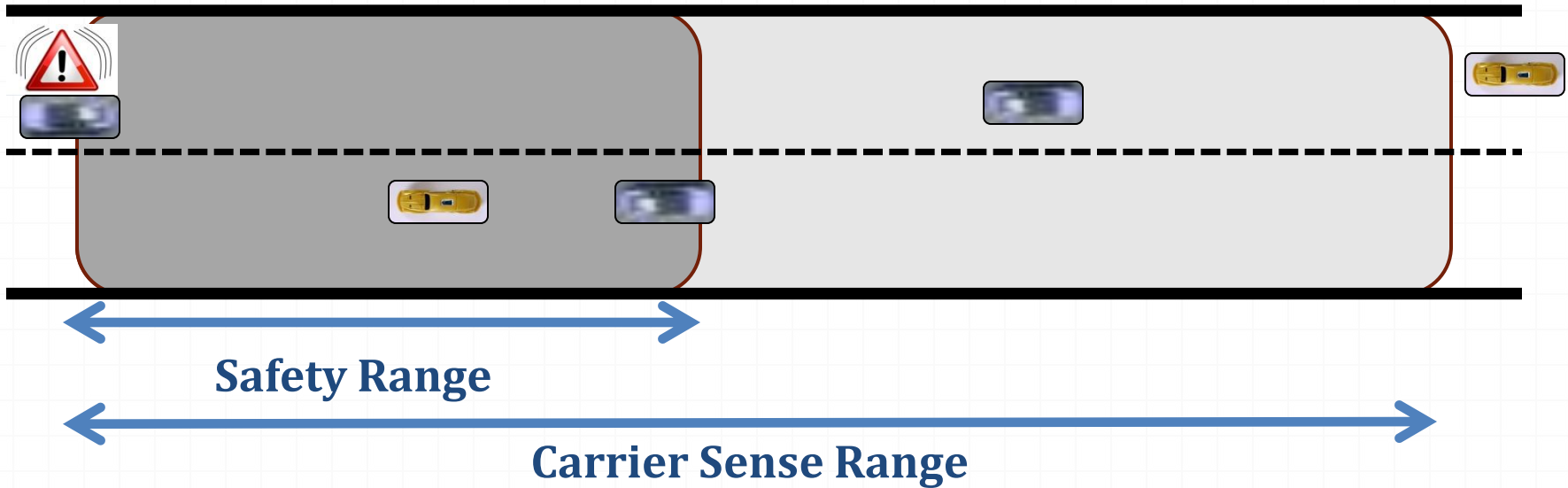
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Carrier Sense vs. Transmission Power



Why Not Use the Minimum Carrier Sense Threshold?



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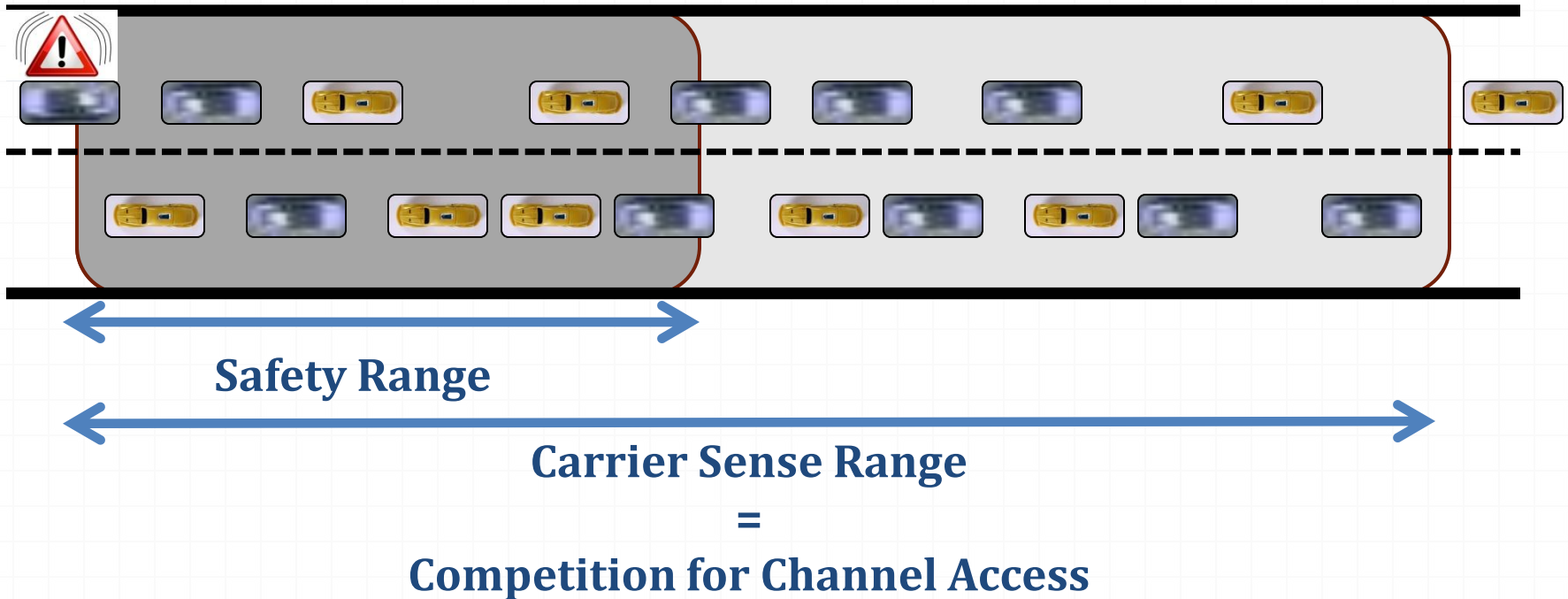
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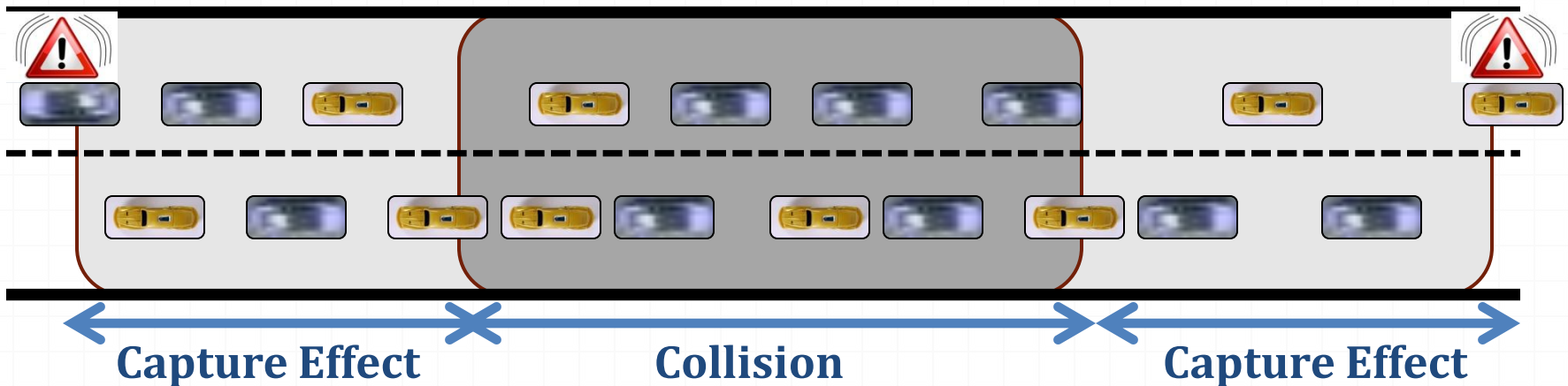
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Vehicular Density

- ❑ More neighbours – longer back-off
- ❑ More neighbours – more expired beacons
- ❑ More neighbours – more collisions



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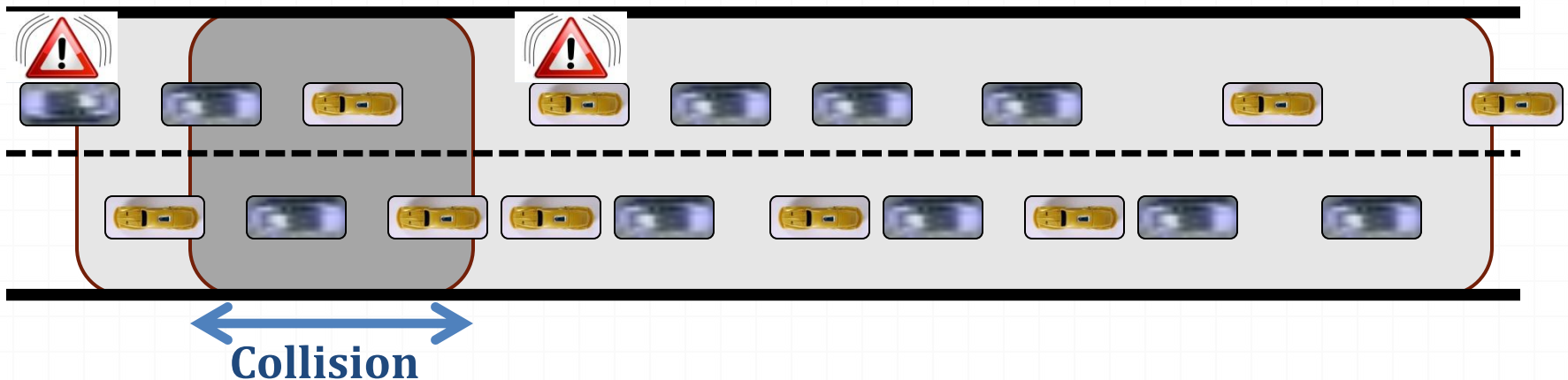
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Adaptive Carrier Sense Threshold

- Low CSt value under low density
- High CSt value under high density
- Beacon-based density estimation - λ
- $CSt = f(\lambda)$

Simulation Study

- JiST/SWANS framework
- Street Random Waypoint mobility model
- Three different real maps from TIGER database
- Medium and high vehicular density

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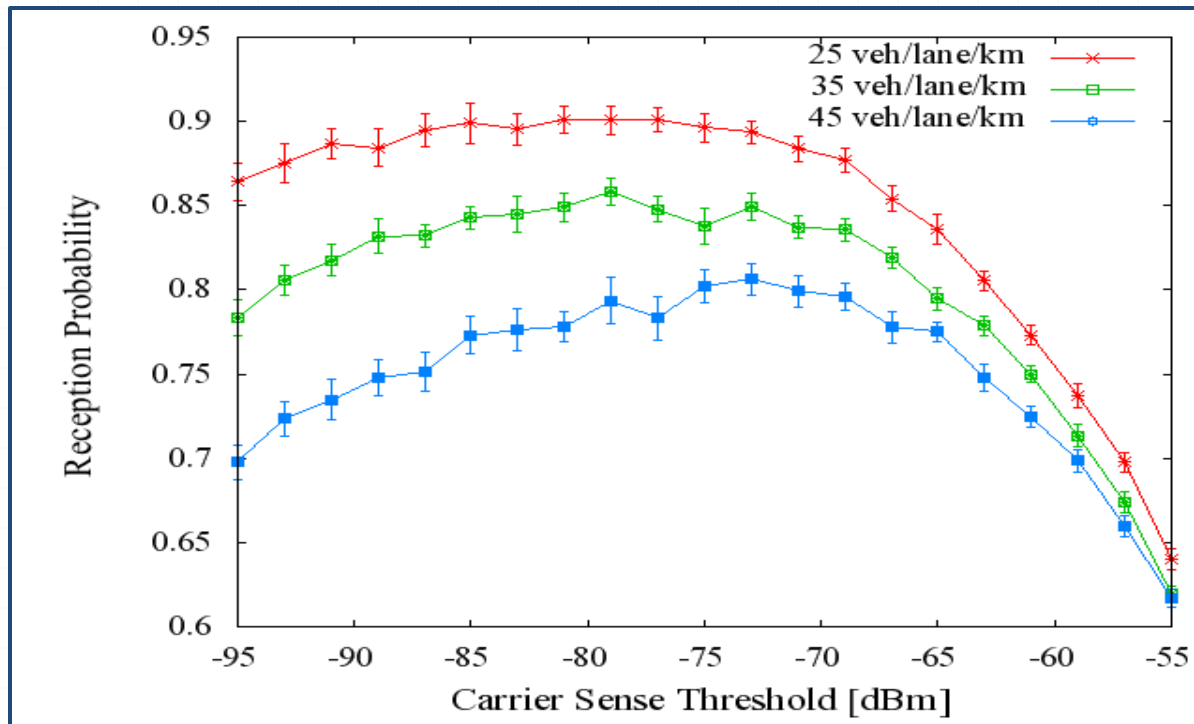
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Beaconing Reception Probability for different Densities and CS Thresholds



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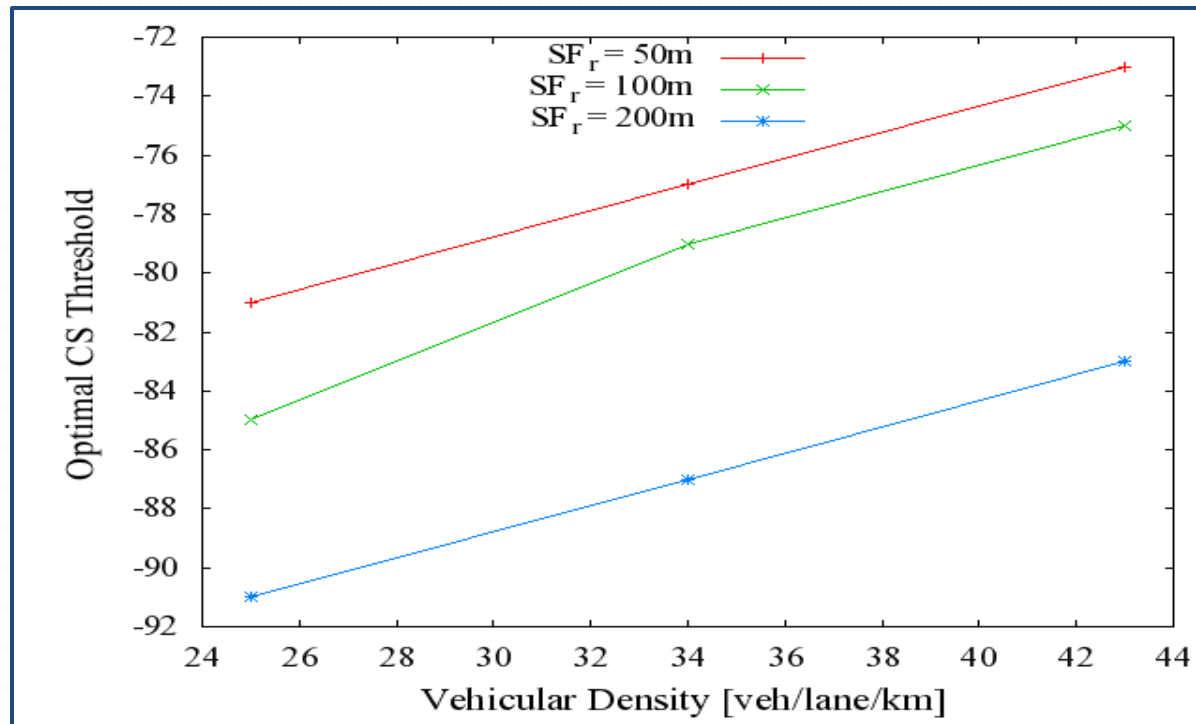
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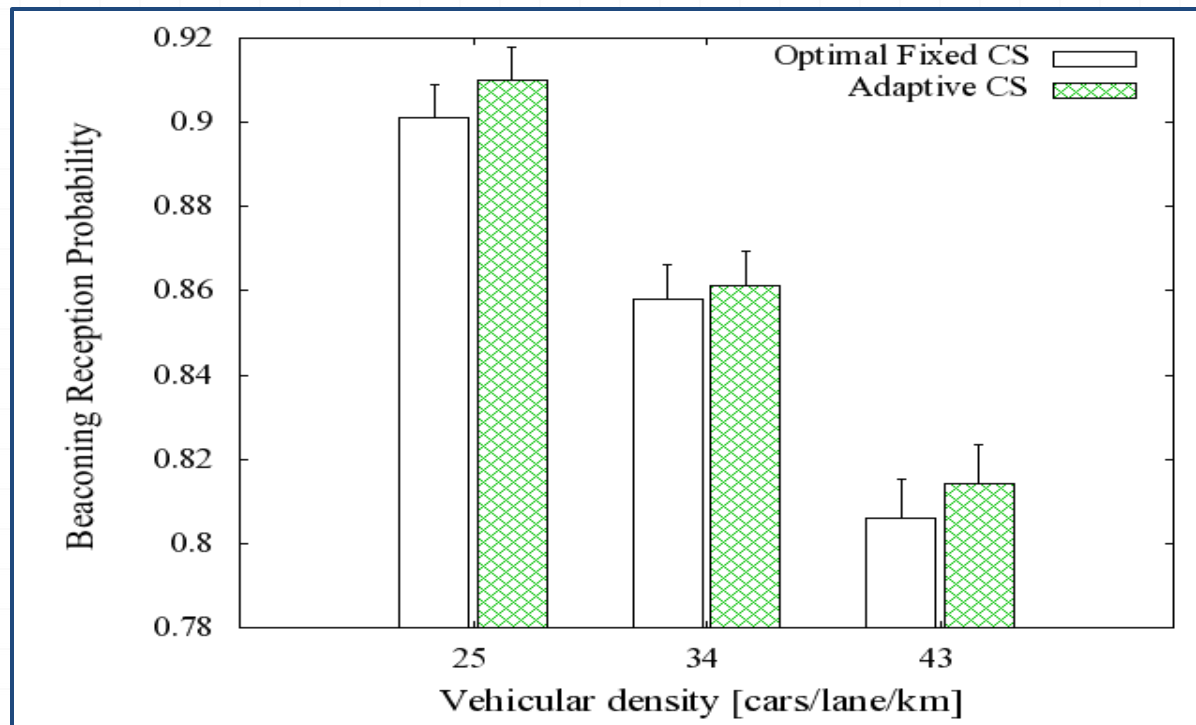
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Impact of the Carrier Sense Range



Adaptive vs. Best Fixed CS



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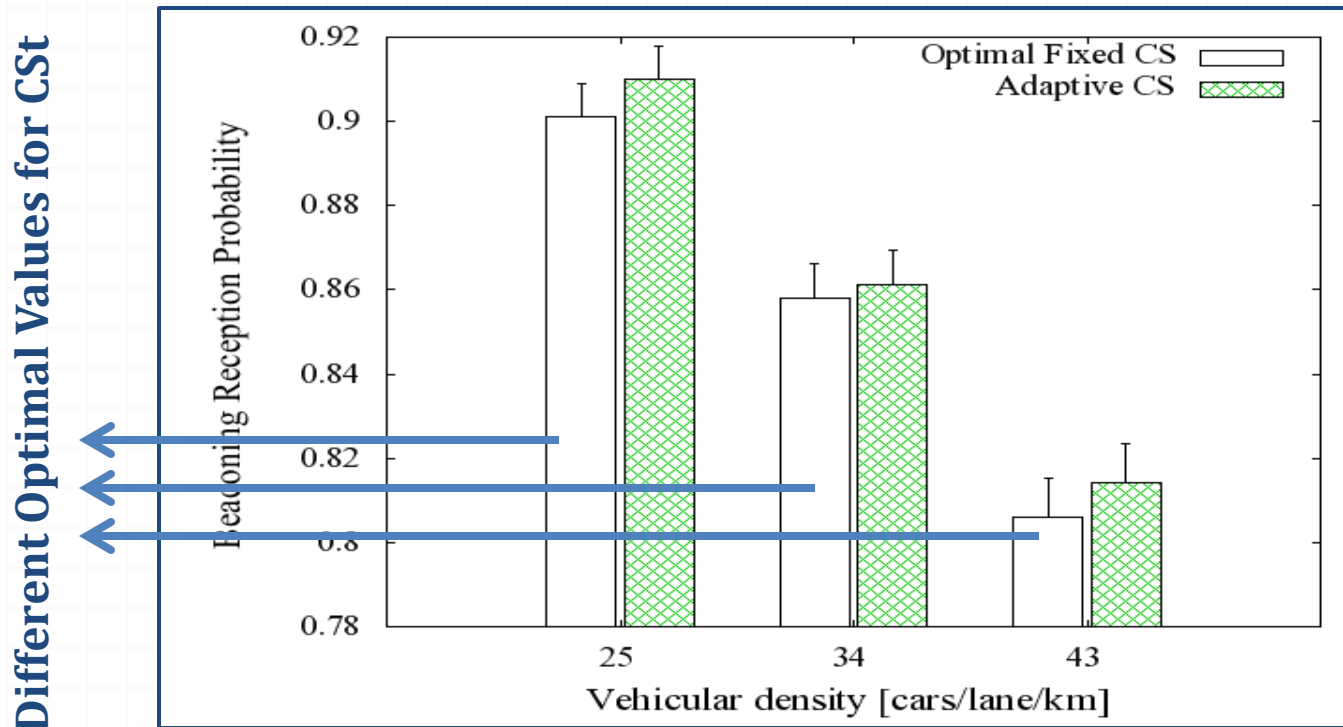
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Adaptive vs. Best Fixed CS



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Physical Carrier Sense in Vehicular Ad-hoc Networks

Adaptive vs. Best Fixed CSt

Vehicular Density	Adaptive Mechanism	CSt= -95 dBm	CSt= -85 dBm	CSt= -75 dBm
25 veh/lane/km	91.02%	86.42%	89.88%	88.64%
35 veh/lane/km	86.12%	78.38%	84.27%	81.81%
45 veh/lane/km	81.41%	69.76%	76.32%	80.20%

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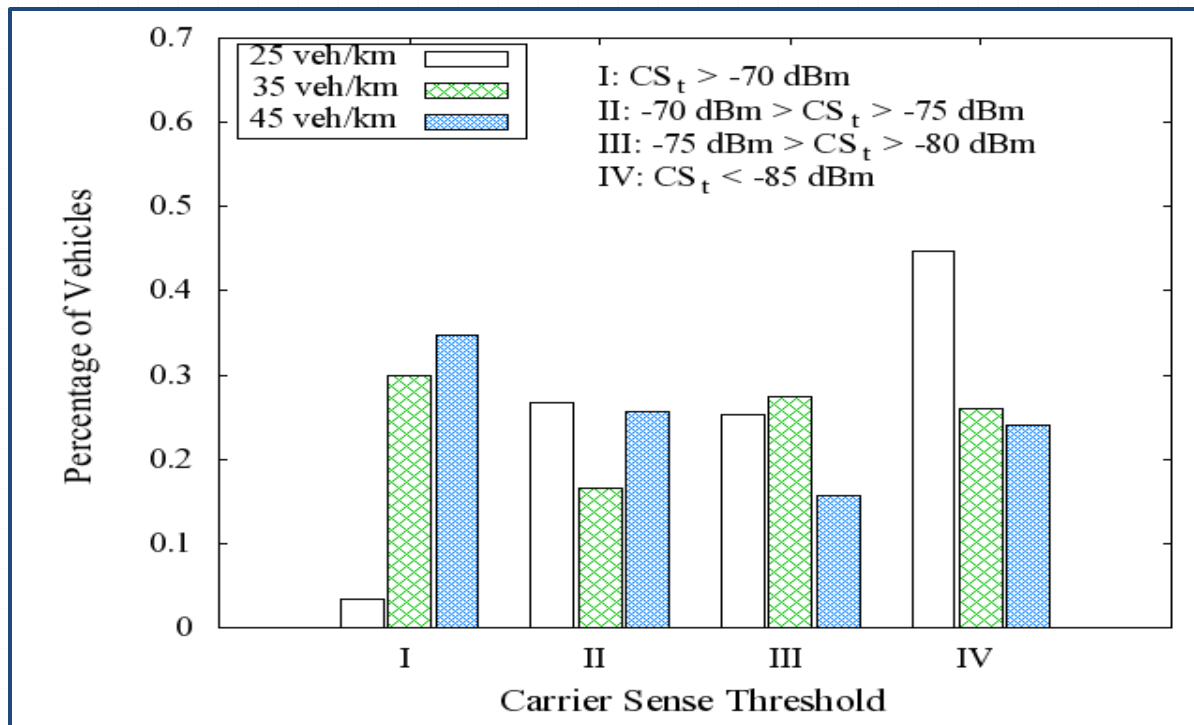
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Distribution of CS_t for the Adaptive Mechanism



Conclusion

- ❑ The properties of the CCH need to be taken into account when studying V2V communication
- ❑ The carrier sense mechanism represents the basis for CSMA/CA channel access techniques and should receive more attention
- ❑ Carrier sense threshold control is more powerful than transmission power control on the VANET CCH
- ❑ A simple adaptive mechanism can bring important performance improvement in IEEE 802.11p networks

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