

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Razvan Stanica, Emmanuel Chaput, André-Luc Beylot

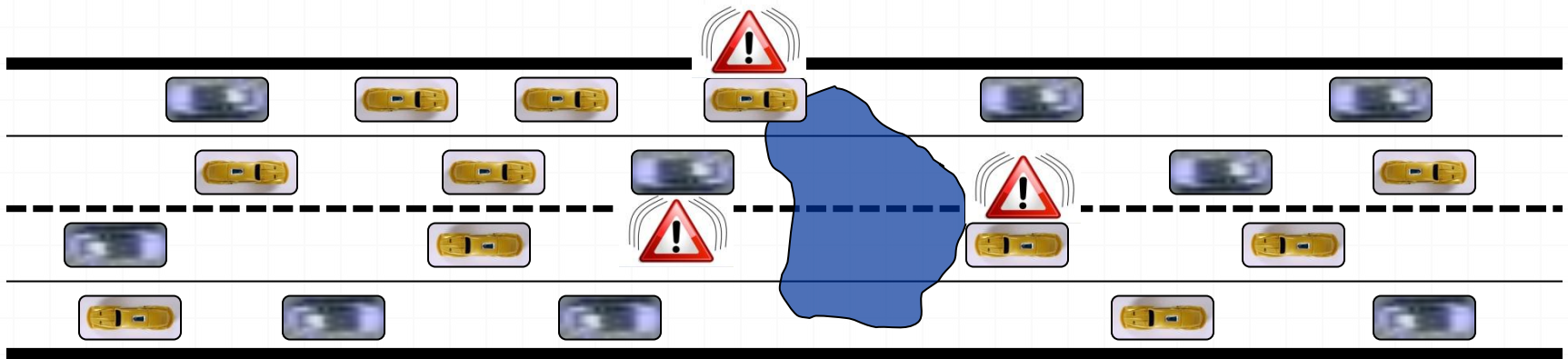
University of Toulouse
Institut de Recherche en Informatique de Toulouse

22nd Annual IEEE International Symposium on Personal, Indoor and
Mobile Radio Communications
Toronto - 12 September 2011



- Safety Communications in Vehicular Networks**
- Minimum Contention Window on the VANET Control Channel**
- Solutions for Local Density Estimation**
- Comparative Results for Adaptive CW Mechanisms**

VANET objective: Building an accurate image of the exterior world



❑ Cooperative Awareness Message (CAM)

❑ Decentralised Environmental Notification (DEN)

Safety V2V

Minimum CW

Adaptive Mechanisms

Results

Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

USA Spectrum Allocation

CH172	CH174	CH176	CH178	CH180	CH182	CH184
5.860	5.870	5.880	5.890	5.900	5.910	5.920
G5SC4	G5SC3	G5SC1	G5SC2	G5CC		

Europe Spectrum Allocation

- ❑ Service channels (SCH) – non-safety (usually IP-based) applications
 - ❑ Control channel (CCH) – safety applications

Safety V2V

Minimum CW

Adaptive Mechanisms

Results

Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

IEEE 802.11p on the CCH

- 100% broadcast communication
- No RTS/CTS handshake
- No ACK message
- Collisions can not be detected
- BEB mechanism deactivated
- Always use the minimum value for CW

Contention Window in unicast IEEE 802.11

- If channel free – send directly
- If channel busy – back off for n idle slots
- $n = \text{random}(0, CW)$
- Initially $CW = CW_{\min}$
- If collision – $CW = CW * 2$

broadcast Contention Window in ~~unicast~~ IEEE 802.11

- If channel free – send directly
- If channel busy – back off for n idle slots
- n= random (0, CW)
- Initially $CW = CW_{\min}$
- ~~If collision – $CW = CW * 2$~~

Bianchi et al. (1996):

□ $CW_{\min} = N\sqrt{(2T_t)}$

□ $T_{\text{idle}} = T_{\text{col}}$

Safety V2V

Minimum CW

Adaptive Mechanisms

Results

Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Bianchi et al. (1996): \longrightarrow Saturated complete networks

□ $CW_{\min} = N \sqrt{2T_t}$

\longrightarrow WLAN size ~ 10 nodes

□ $T_{\text{idle}} = T_{\text{col}}$

\longrightarrow RTS/CTS handshake

Beacon Based

- Extends the Bianchi relationship
- Uses received beacons to estimate density
- $CW = \lambda N$
- Lost beacons can impact the result

Collided Packets

- ❑ Uses sequence numbers to estimate PER
- ❑ If $PER < PER_{min}$ – increase CW
- ❑ If $PER > PER_{max}$ – decrease CW
- ❑ Compatibility problem with privacy framework based on pseudonyms

Idle Time

- ❑ Estimate T_{col} using the number of lost messages
- ❑ If $T_{col} > \alpha T_{idle}$ - increase CW
- ❑ If $T_{idle} > \alpha T_{col}$ - decrease CW
- ❑ Compatibility problem with privacy framework based on pseudonyms

Stop Time

- ❑ Based on relationships from traffic flow theory
- ❑ Measure the time a vehicle is stopped
- ❑ $CW = (T_{\text{stop}} / T_{\text{update}})(CW_{\text{max}} - CW_{\text{min}}) + CW_{\text{min}}$
- ❑ A vehicle could stop for other reasons, unrelated to the traffic state

Speed Based

- ❑ Using speed information can be useful in intermediate states
- ❑ Measure vehicular jerk (the derivative of the acceleration)
- ❑ $CW = (|jerk| / speed / D_{max})(CW_{max} - CW_{min}) + CW_{min}$
- ❑ Jerk is not currently measured by vehicles

Simulation Study

- JiST/SWANS framework
- Street Random Waypoint mobility model
- Three different real maps from TIGER database
- Medium and high vehicular density

Safety V2V

Minimum CW

Adaptive Mechanisms

Results

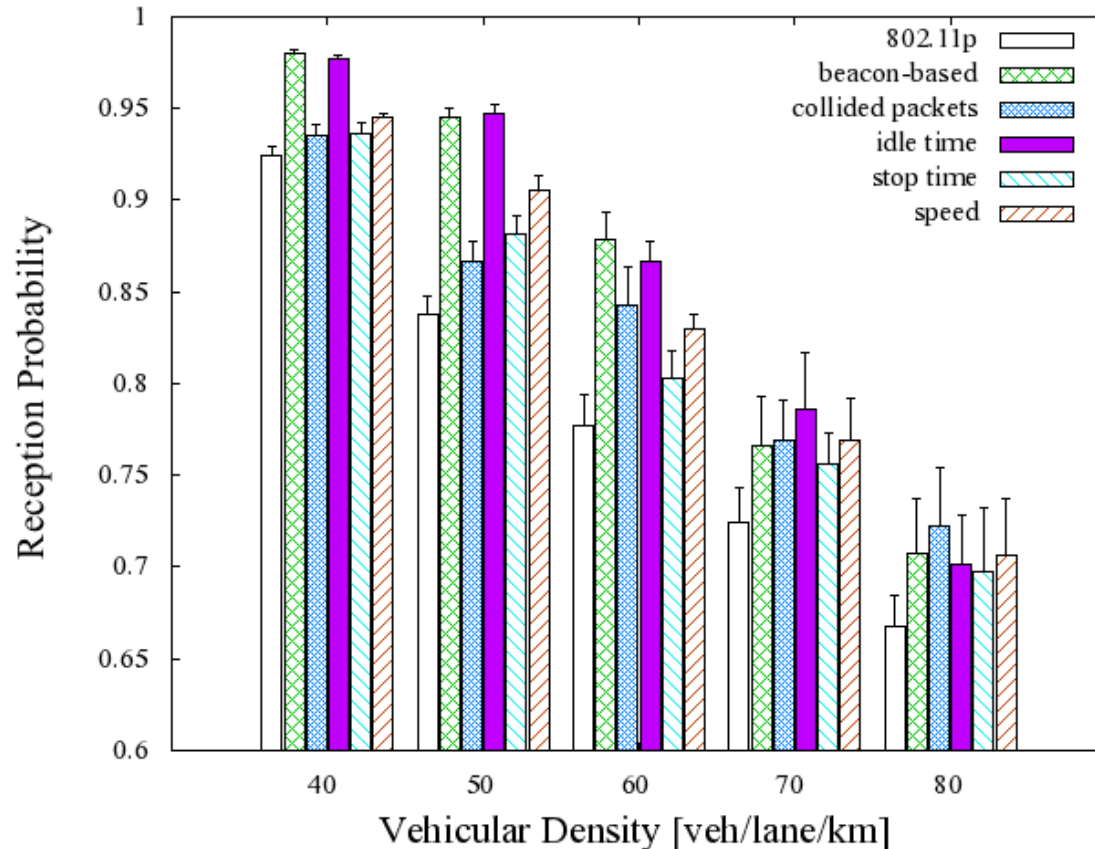
Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Beaconing Reception Probability at less than 200m from the Sender



Safety V2V

Minimum CW

Adaptive Mechanisms

Results

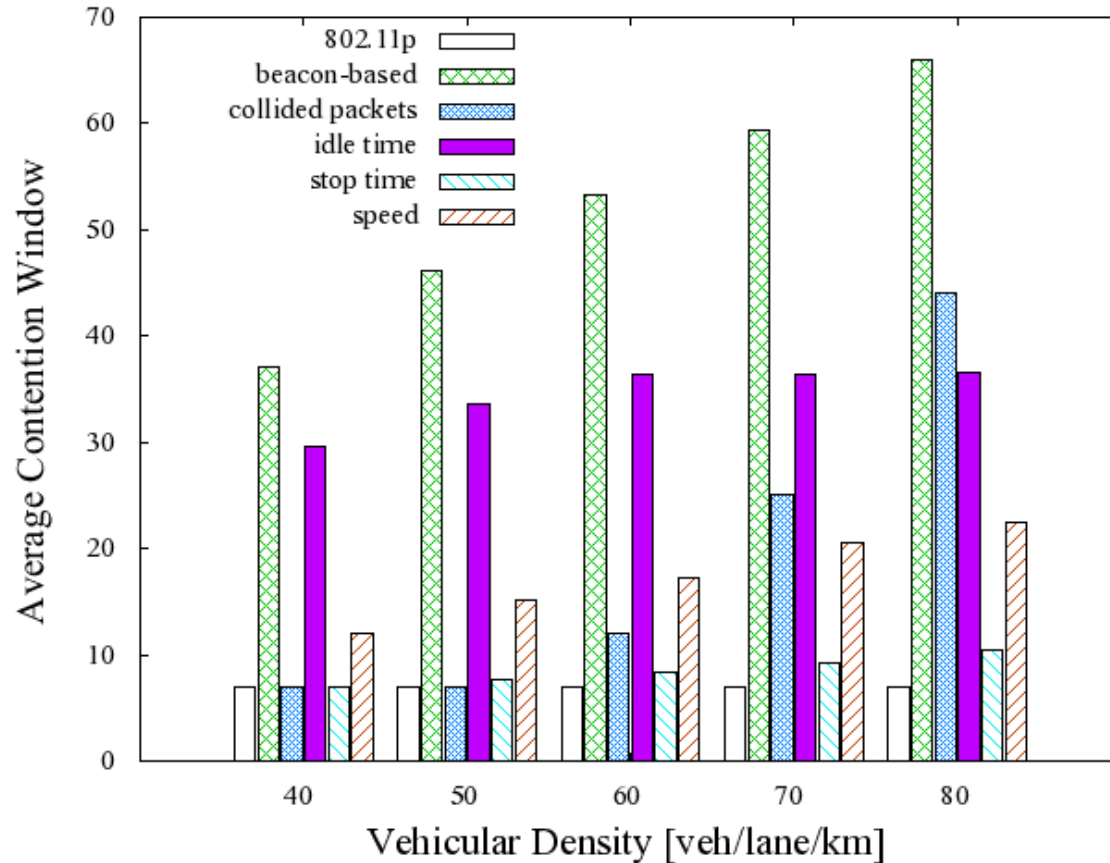
Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Average Contention Window for the different Mechanisms



Safety V2V

Minimum CW

Adaptive Mechanisms

Results

Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Observations

- All the mechanism show an important improvement over the current version of the standard
- The same results can be obtained using different strategies
- Solutions based on traffic flow theory are efficient when the vehicular density increases
- These heuristics are quite simple and they could be straightforwardly integrated in the standard

Safety V2V

Minimum CW

Adaptive Mechanisms

Results

Razvan Stanica

University of Toulouse

PIMRC 2011

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Conclusion

- ❑ The properties of the CCH need to be taken into account when studying V2V communication
- ❑ The contention window of the back-off mechanism is a very important parameter for MAC layer congestion control
- ❑ This work compares the performance of five adaptive mechanisms specially conceived for VANETs

Local Density Estimation for Contention Window Adaptation in Vehicular Networks

Razvan Stanica, Emmanuel Chaput, André-Luc Beylot

University of Toulouse
Institut de Recherche en Informatique de Toulouse

22nd Annual IEEE International Symposium on Personal, Indoor and Mobile Radio Communications
Toronto - 12 September 2011

